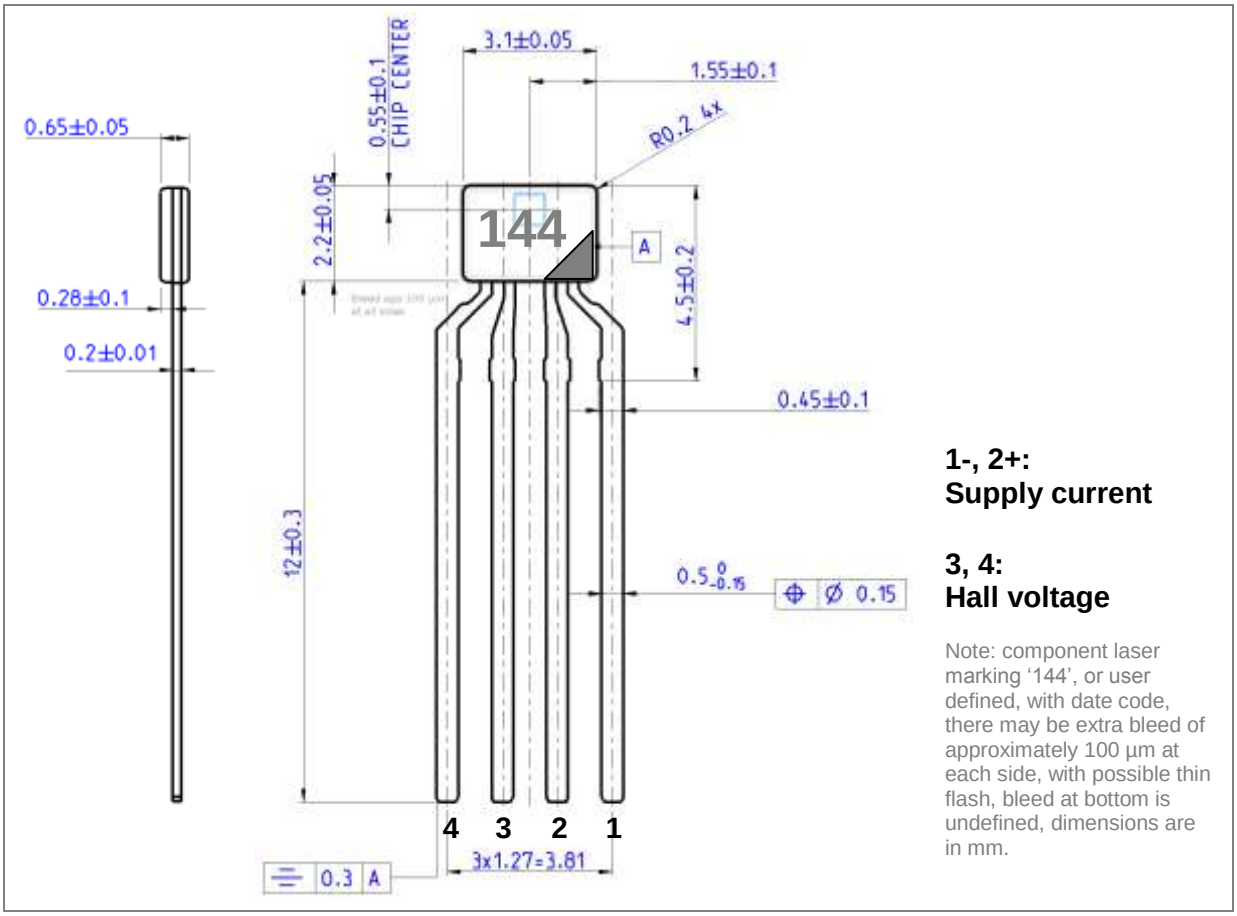
HE144 series Hall sensors

Pin compatible with Siemens® / Infineon®
KSY14 and KSY44 Hall sensors



Features

- Precise tracking between sensors
- Large range, including strong fields
- Very small linearity error
- Low TC of sensitivity and drift
- Low noise, low drift
- Low EMC pickup
- High sensitivity
- Very low Planar Hall Effect (PHE) error
- Wide operating temperature range
- Very flat miniature package
- Low inductive zero component

Typical applications

- Multi-sensor and differential usage
- Current and power measurement
- Magnetic field measurement
- Rotation sensing
- Position sensing
- Measurement of distances
- Measurement of diaphragm
- 3D compass
- Movement sensing
- Measurement of pressure
- Control of motors

Two enclosures are available "off the shelf": one that is compatible with the Infineon® KSY14 and KSY44 Hall sensors, and a SMD version. These are "green" devices, RoHS, lead free, and compliant with Japanese demands. The text on the device can be customer specific, depending on the type. A date and manufacturing code will be added.

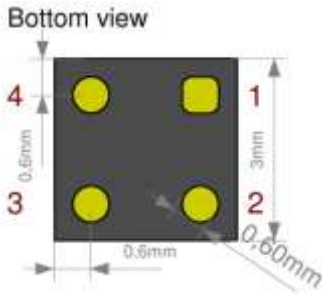
Surface plating

- RoHS gold plated is the standard plating
- RoHS matte tin, electrochemical plated, is possible on demand
- RoHS tin dipped, tin-silver-copper, is possible on demand
- Leaded (non-RoHS), electro-chemical plated, is possible on special demand
- Leaded (non-RoHS), dipped, is possible on special demand

Gold plating ensures better shelf lives, and prevents tin whiskers.

"SMD" version

The Hall sensors are also available in a small BGA-like (ball-less) package. The thickness of the component is approximately 0.6 mm. Thickness can be adjusted to customer requirements, down to 0.4 mm. Thermal data (see below) does not apply here.
Use BGA soldering methods.



The pads are gold plated. The parts are RoHS. Use normal soldering methods. Pin1 is the – supply current, pin 2 is the + supply current, pin 3 and 4 are the Hall outputs.

Other packages and sensors

We can create any package you want, we can design and create packages, also specials and ceramics, even with 0.4 mm thickness. And we can use other sensor dice in our non-magnetic packages, like GMR or AMR magnetoresistive sensors, or include temperature sensors.

Electrical parameters

Absolute Maximum Ratings

Parameter	**Symbol**	**Value**	**Unit**
Operating temperature range[I]	T_A	-40 to +175	°C
Storage temperature rate[I]	T_{stg}	-50 to +180	°C
Supply current[II], note: see Advised current	I_1	10	mA
Characteristics, preliminary (T_A = 25°C)			
Thermal Conductivity in air	G_{thA}	≥ 1.5 typical 1.8	mW/K
Thermal Conductivity soldered	G_{thC}	≥ 2.2 typical 3.4	mW/K
Nominal Supply Current	I_{1N}	5	mA
Advised supply current (S/R optimal, range)	I_{1A}	0 to 1	mA
Open-circuit Sensitivity[III]	K_{B0}	180..370	V/AT
Open-circuit Hall Voltage[IV] $I_1 = I_{1N}$, $B = 0.1$ T	V_{20}	90…185 typical 100	mV

Temperature coefficient of the open-circuit Hall voltage, $I_1 = I_{1N}$, $B = 0.2$ T @25°C		TC_{V20}	± 0.02 typical -0.003	%/K
Ohmic Offset Voltage[V], $I_1 = I_{1N}$, $B = 0$ T *Note: temporary spec, to be changed to typical ≤ ± 5 mV in later versions*		V_{R0}	≤ ± 60 |typical| 50 mV	mV
Temperature coefficient of the Ohmic Offset Voltage, $I_1 = I_{1N}$, $B = 0$ T		TC_{VR0}	±0.2 typical ~-0.06@25°C	%/K
Maximum change of the Ohmic Offset Voltage within the temperature range		$\lvert \Delta V_{R0} \rvert$	± 2 typical ± 0.3@0-50°C	mV
Drift of Ohmic Offset Voltage, $I_1 = I_{1N}$, $B = 0$ T	0.1 to 1.0 sec. after power up	dV_0	not specified	mV
	1.0 sec to 3 min. after power up	ΔV_0	not specified	mV
Supply side internal resistance[VI], $B = 0$ T		R_{10}	900...1250 typical 1000	Ω
Temperature coefficient of the Supply side internal resistance, $B = 0$ T		TC_{R10}	typical 0.35	%/K
Hall side internal resistance[VII], $B = 0$ T		R_{20}	900...1700 typical 1000	Ω
Temperature coefficient of the Hall side internal resistance, $B = 0$ T		TC_{R20}	typical 0.35	%/K
Linearity of Hall voltage	$B = 0…0.5$ T	$\Delta V_{20\text{-}0.5}$ (or $F_{L\text{-}0.5}$)	≤ ± 0.2 typical ≤ ± 0.1	%
	$B = 0…1.0$ T	$\Delta V_{20\text{-}1}$ (or $F_{L\text{-}1}$)	≤ ± 0.7 typical ≤ ± 0.1	%
	$B = 0…2.4$ T, $I_1 = 1$ mA	$\Delta V_{20\text{-}2}$ (or $F_{L\text{-}2}$)	limit not specified typical ≤ ± 0.2	%
Bandwidth (-3dB point)		B	not specified yet	kHz
Rise time			not specified yet	
Noise figure[VIII]		F	≤ 10	dB

[I] In fact capable of a much larger temperature range, contact us for more information
[II] Allowed and advised to be smaller than 5 mA, leads to better noise behaviour and less drift
[III] Data subject to change
[IV] Data subject to change
[V] Will be improved in later parts, first series are typical 10 mV@1mA, but with very low temperature drift
[VI] Tracking devices follow delivered values typically within ± 30 milliOhm
[VII] Tracking devices follow delivered values typically within ± 30 milliOhm
[VIII] At advised current, contact us for advise

All data is subject to change without prior notice, future versions may be improved

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